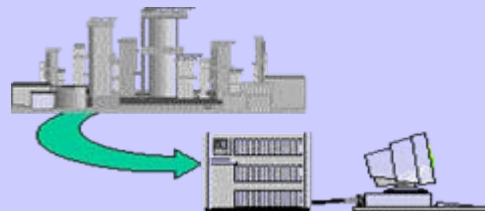


APS Forum  
Balatonfüred, May 25-26<sup>th</sup> 2011

# SOFT SENSORS APPLICATION IN PROCESS INDUSTRY



**Nenad Bolf** Assoc. Prof.

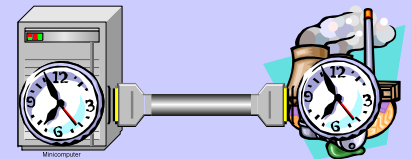
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# MEASUREMENT PROBLEMS

- ✚ Difficult to provide reliable, fast, on-line measurements to control product quality
- ✚ The quality measure may only be available as a **laboratory analysis** or very **infrequently on-line**
  - Lead to excessive **off-specification** of products

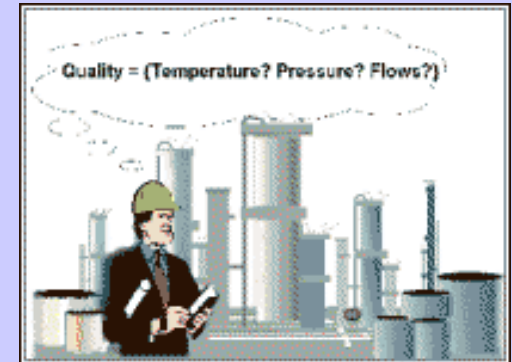
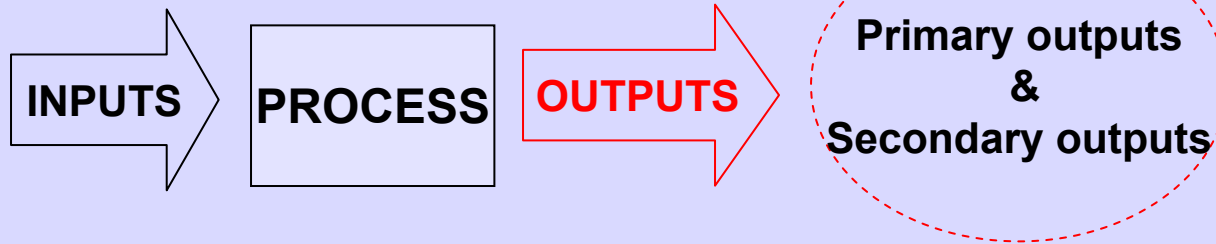
- ✚ **Reliability of on-line instruments**  
(drifting, fouling, sample system failure etc.)



**Automatic control** and **optimisation** schemes cannot be implemented.

# MEASUREMENT PROBLEMS

- Productivity is quantified by specifications upon which the product is sold - e.g. **purity**, **physical** or **chemical properties**  
→ **primary variables** – difficult to measure on-line



- ✚ The other outputs (e.g. **temperature**, **flow** and **pressure**)  
→ **secondary variables** - easily measured on-line

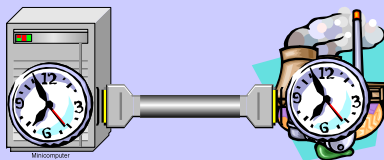
# POSSIBLE SOLUTIONS

## MANUAL CONTROL

- ✚ common approach to effecting control on the process is to control it **manually**

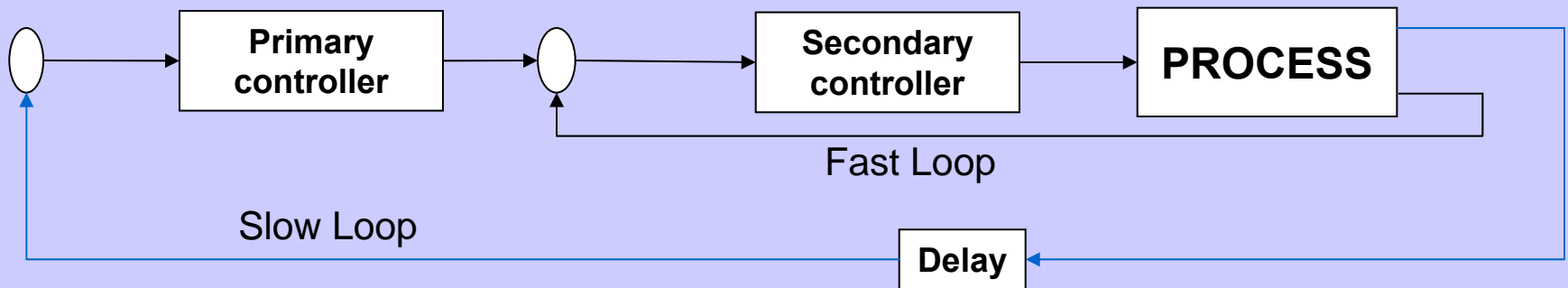


- ✚ Return of information for control purposes from laboratory is **slow** and **irregular**
- ✚ Its success depends on the operator's **training** and **experience**



# POSSIBLE SOLUTIONS

## PARALLEL CASCADE CONTROL



- ✚ The slow loop dictated by the delay of a measurement device
- ✚ Assumption:  
If the **secondary** variable is kept at some value, then the **primary** variable also be kept at some level
- ✚ Slow loop is used to correct (trim) the set-point of the secondary loop

# Parallel Cascade Control

- ✚ often employed in the product composition control of **distillation columns**
- ✚ Two control loops:
  - fast **secondary** loop - a **tray temperature**
  - slow **primary** loop - **product composition**

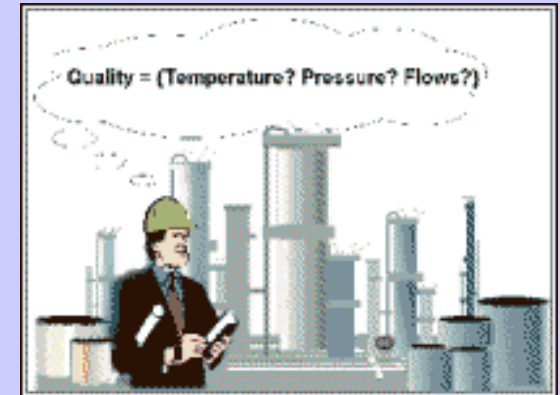
## Drawbacks

- ➡ **Disturbances** affecting the secondary variable may not affect the primary variable
- ➡ The relationship between the primary and secondary variables is **non-linear**, and can change depending on the **operating conditions**

# POSSIBLE SOLUTIONS

## INFERENCEAL MEASUREMENT

allows process quality, or a difficult to measure process variables, to be inferred from other **easily made plant measurements** such as pressure, flow or temperature.



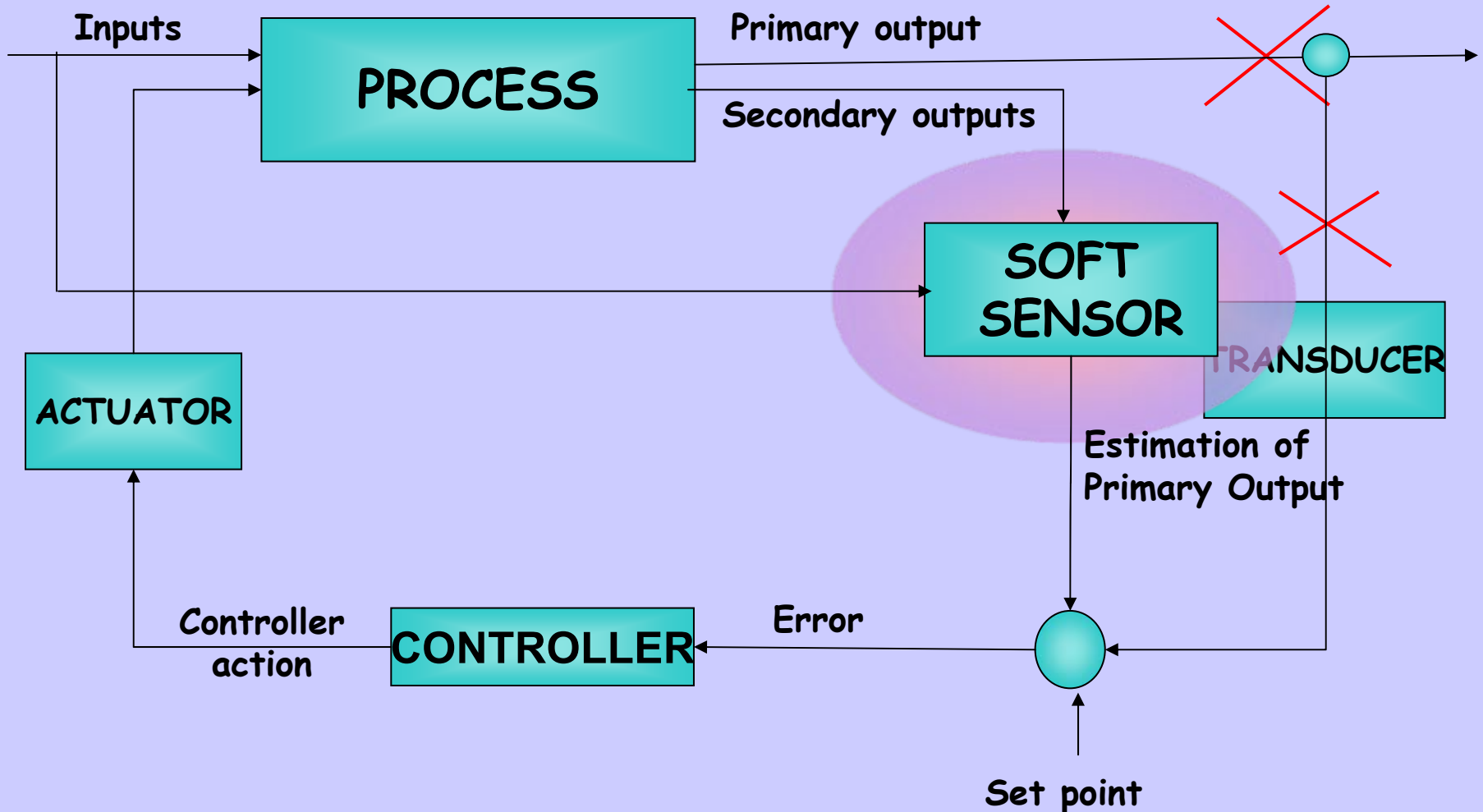
## SOFT(WARE) SENSOR

**Model which estimates unmeasurable process states based on easy to measure input and output variables.**

## KEY WORDS & SYNONYMS

software sensor, virtual soft sensor, smart sensor  
virtual analyzer, inferential control

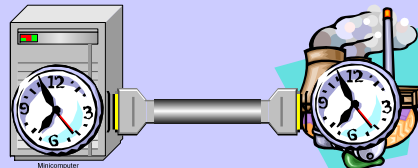
# SOFT SENSOR AND INFERENTIAL CONTROL



# Criteria for soft sensor application

## Inferential variable must satisfy the following criteria:

- ❏ Good **relationship** to true **controlled variable** for changes in the potential **manipulated variable**
- ❏ **Insensitive** to changes in **operating conditions** and unmeasured disturbances
- ❏ **Dynamics** must be acceptable for use in **feedback control**



# Types of models for soft sensor developing

## First principle models

- Based on balance and phenomenological equations
- Process knowledge required
- Comparatively expensive

## Data driven models

- Identified using process data
- Comparatively inexpensive

# Model structures and identification techniques

	Steady state	Dynamic
Models	<ul style="list-style-type: none"><li>• Multiple Linear Regression</li><li>• PCA and PLS</li><li>• Neural Networks</li></ul>	<ul style="list-style-type: none"><li>• Finite Impulse Response</li><li>• ARX, ARMAX, OE, BJ, ...</li><li>• ...</li></ul>
Identification	<ul style="list-style-type: none"><li>• Least Squares</li><li>• Backpropagation</li><li>• Numerical optimization</li></ul>	<ul style="list-style-type: none"><li>• Least Squares</li><li>• Subspace identification</li><li>• Prediction error methods</li><li>• Numerical optimization</li></ul>

# SOFT SENSOR MODEL DEVELOPMENT

## SYSTEM IDENTIFICATION METHODS

Regressors	Linear model	Nonlinear model
$u(k-i)$	FIR	NFIR
$u(k-i), y(k-i)$	ARX	NARX
$u(k-i), \hat{y}(k-i)$	OE	NOE
$u(k-i), y(k-i), e(k-i)$	ARMAX	NARMAX
$u(k-i), y_s(k-i), e(k-i) \text{ i } e_s(k-i)$	BJ	BJ

$$y(k) = f[u_1(k-1), \dots, u_1(k-n_1), u_2(k-1), \dots, u_2(k-n_2), \dots, u_m(k-1), \dots, u_m(k-n_m)]$$

$$y(k) = f[y_1(k-1), \dots, y_1(k-n_1), y_2(k-1), \dots, y_2(k-n_2), \dots, y_m(k-1), \dots, y_m(k-n_m)]$$

**FIR** – Finite Impulse Response model

**ARX** – Auto Regressive model with exogenous inputs

**OE** – Output Error model

**ARMAX** – Auto Regressive Moving Average model with exogenous inputs

**BJ** – Box - Jenkins model

# DEVELOPING DATA-DRIVEN MODELS

- Feasibility
- Requirements
- Experiences

- Integration of knowledge
- Linear / non linear
- Steady-state / dynamic

- Noise
- Disturbances
- Maintenance

Preliminary investigation

Pre-processing raw data

Model structure selection and parameter estimation

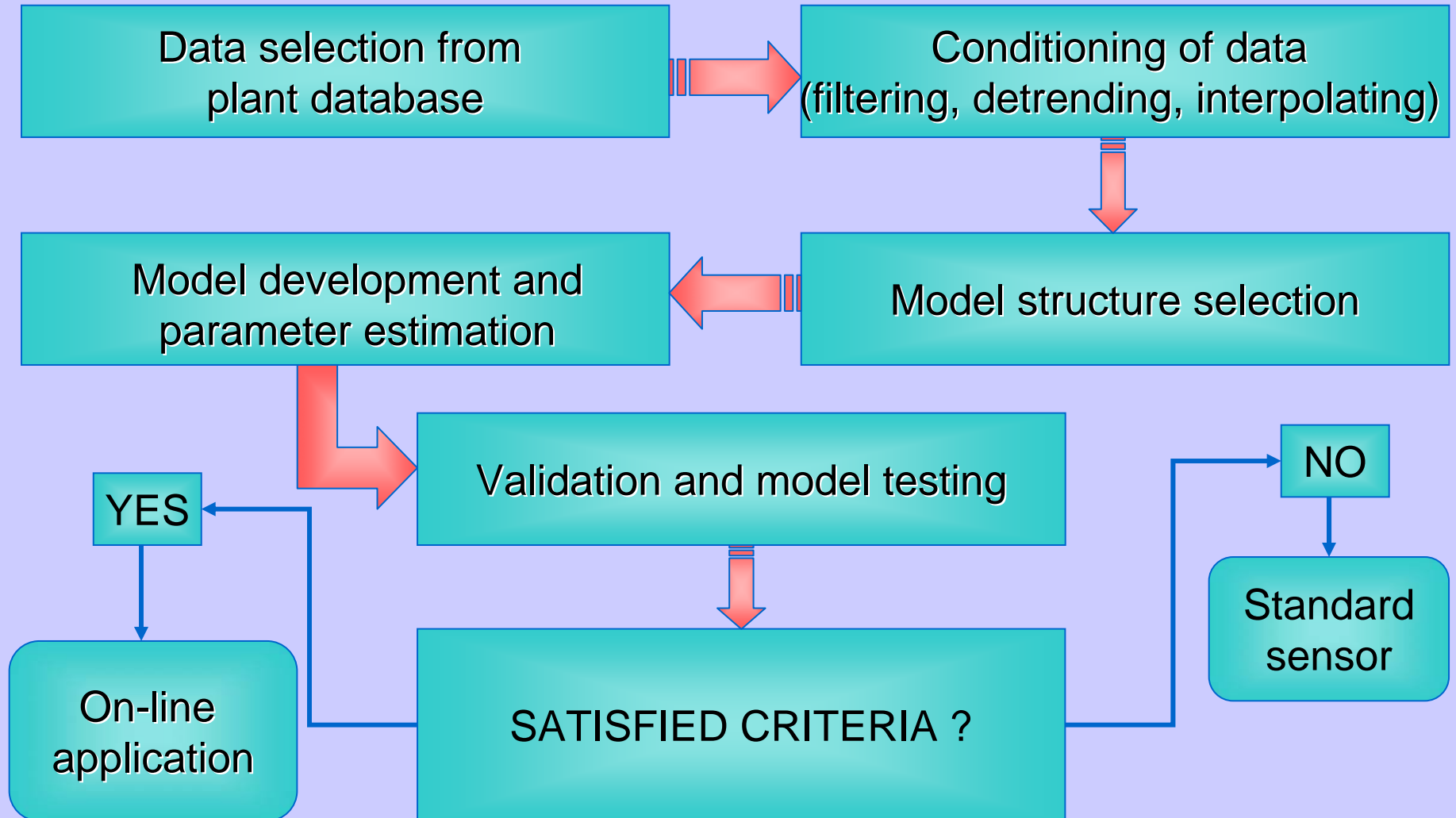
Fine tuning and confidence interval

Online application

- Validation
- Interpolation
- Outlier detection

- Analysis
- Sensitivity analysis

# SOFT SENSOR DESIGN PROCEDURE

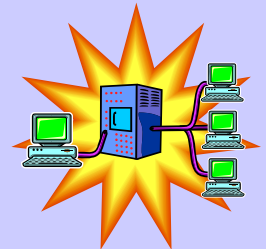


# INDUSTRIAL APPLICATION

## Back Up of Measuring Devices

during failures, maintenance, services etc.

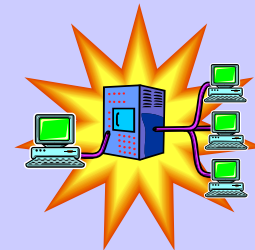
- **harsh working environment** and robust measuring hardware
- an inferential model for substituting **unavailable measuring equipment**
- two possible choice of model structure:
  - **MA** or **NMA** models which do not require past samples of the output variable (FIR)
  - **AR** as infinite-step-ahead predictors



# INDUSTRIAL APPLICATION

## Reducing the Measuring Hardware Requirements

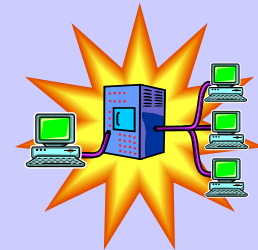
- software tools which substitute measuring hardware devices
- **NMA** models should be preferred to **AR** structures
- the problem is lack of any redundancy



# INDUSTRIAL APPLICATION

## Real-time Estimation for Monitoring and Control

- long analyze time delay and transportation delay
- delay in the time in which data are presented to operator
- allows the use of **ARX** and **NARX** model structures for finite step-ahead prediction



# INDUSTRIAL APPLICATION

## Sensor Validation, Fault Detection and Diagnosis

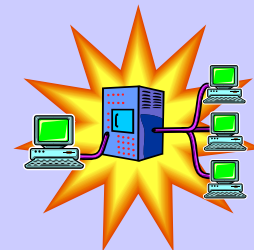
- part of the supervision functions in the control systems
- comparing information collected from the system with the corresponding information from a **redundant source**
- **the main goals:**
  - early **detection of faults**
  - provide a **decision support system** for scheduled, preventive or predictive maintenance and repair
  - base for the development of fault-tolerant systems



# INDUSTRIAL APPLICATION

## What-if-Analysis

- models that predict the system output to suitable input trends for a given time span
- simulation of the system dynamics to input trends of interest
- **NARX** models with finite time span used in simulations



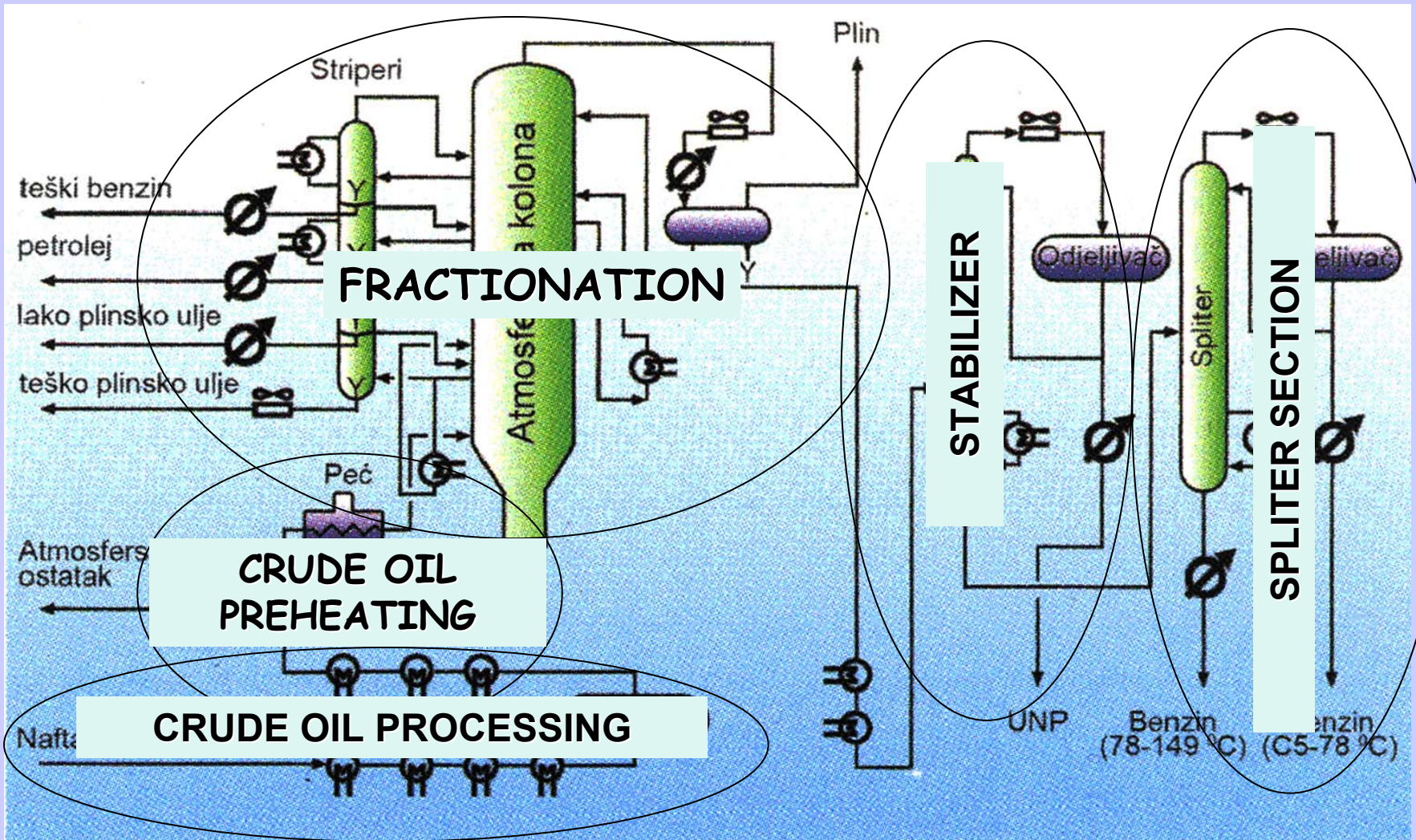
# Case Study

## CRUDE DISTILLATION UNIT

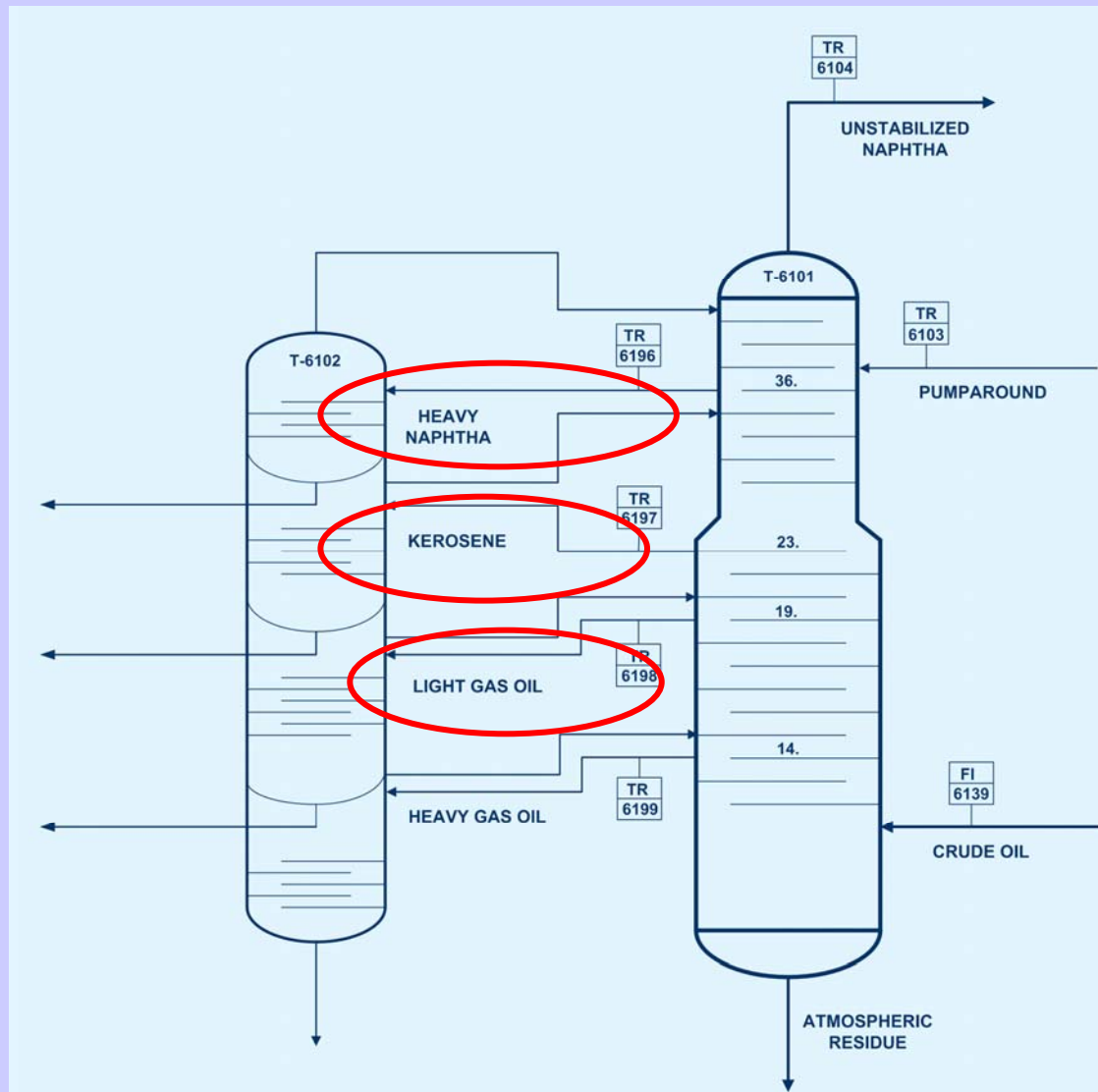
### INA-SISAK REFINERY



# CRUDE DISTILLATION UNIT



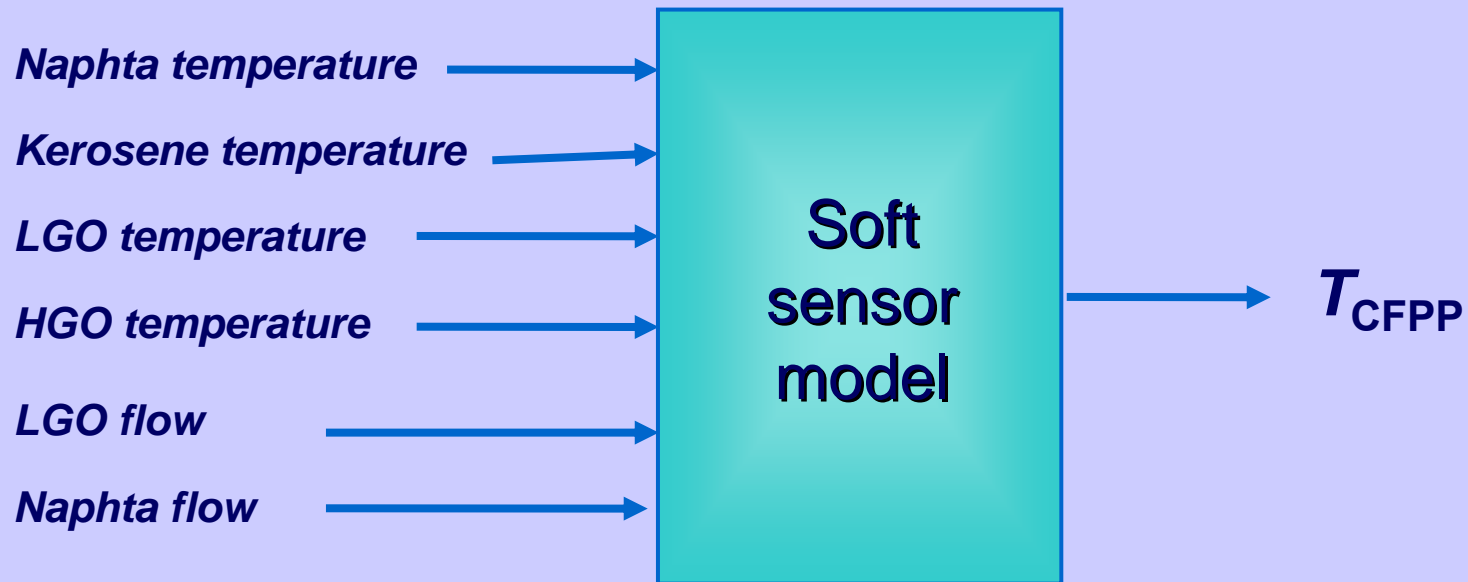
# DIESEL FUEL SOFT SENSOR MODELS



# DIESEL FUEL SOFT SENSOR MODELS

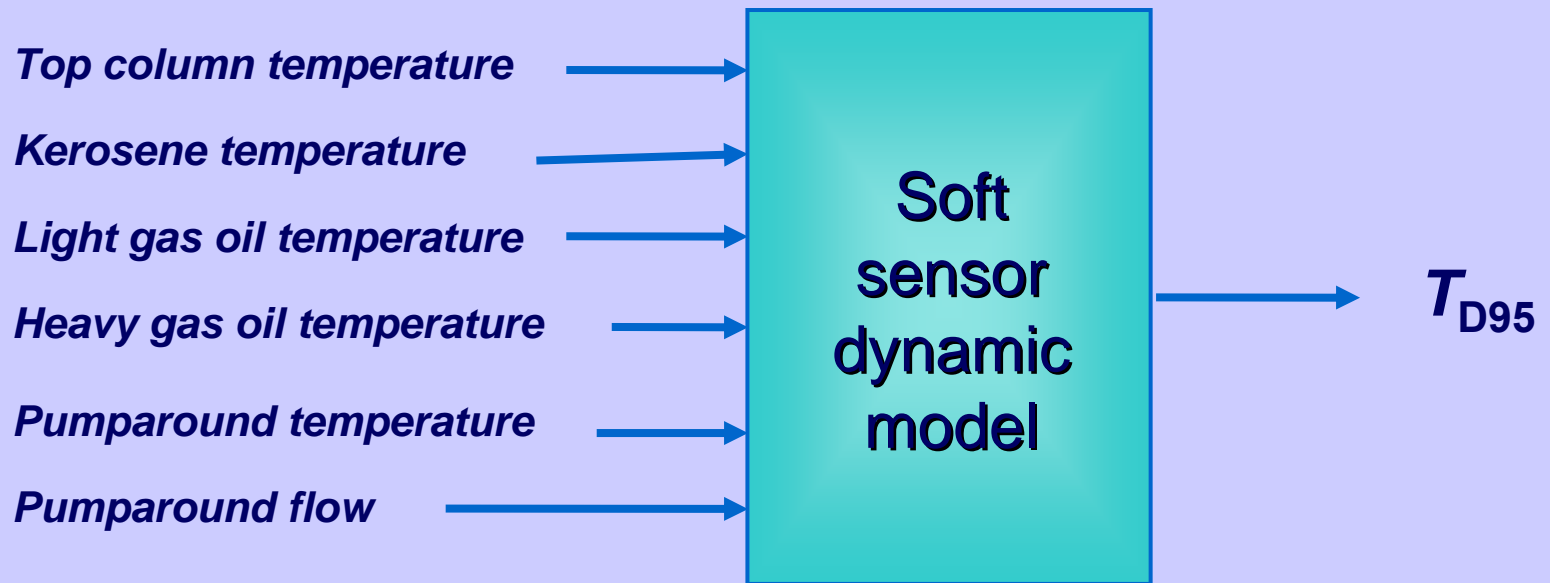
- Developed models for:
  - **Cold filter plugging point** estimation (CFPP)
  - **Distillation end point** estimation (D95)
- Models are developed using:
  - multiple linear regression
  - neural networks (MLP, RBF)

# Neural network model structure for CFPP



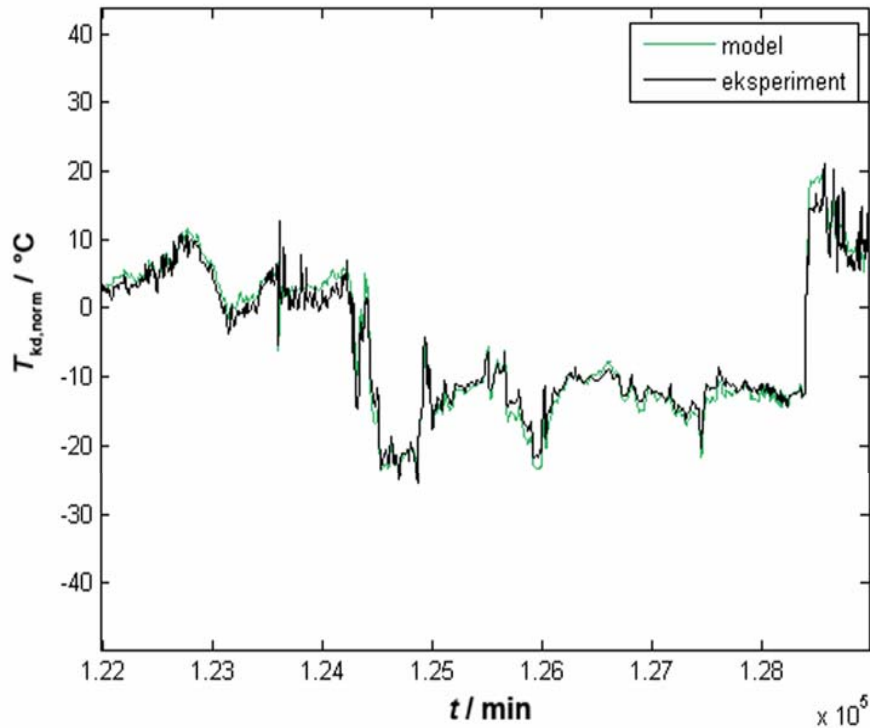
Multilayer perceptron neural network

# SOFT SENSOR FOR DISTILLATION END POINT



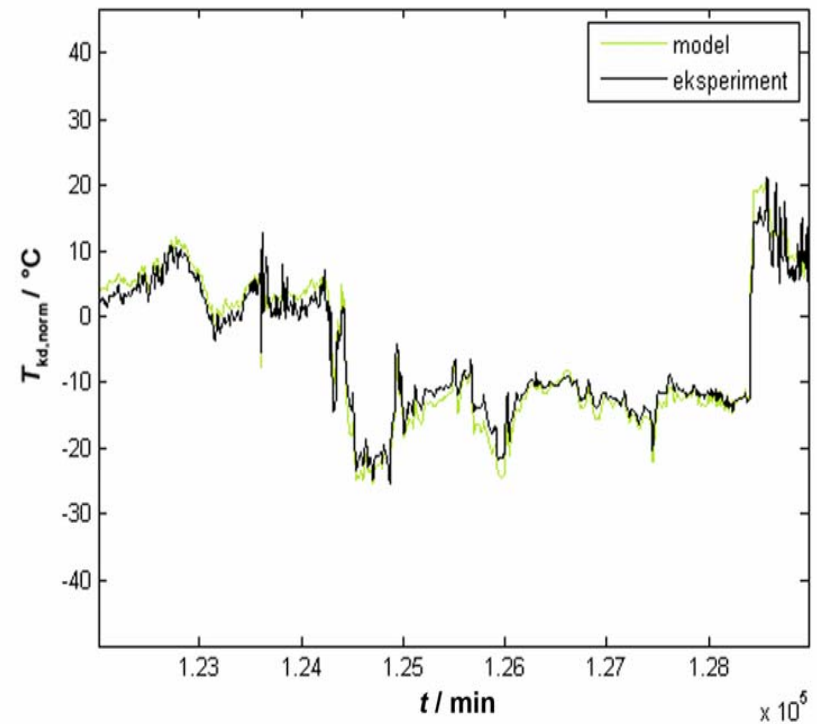
# RESULTS – linear dynamic model (D95)

## ARMAX model



<b><i>FIT PRED.</i></b>	<b><i>FPE</i></b>	<b>MODEL PARAMETER</b>
89,46	1,58	na = 3, nb = 3, nc = 6, nk = 0

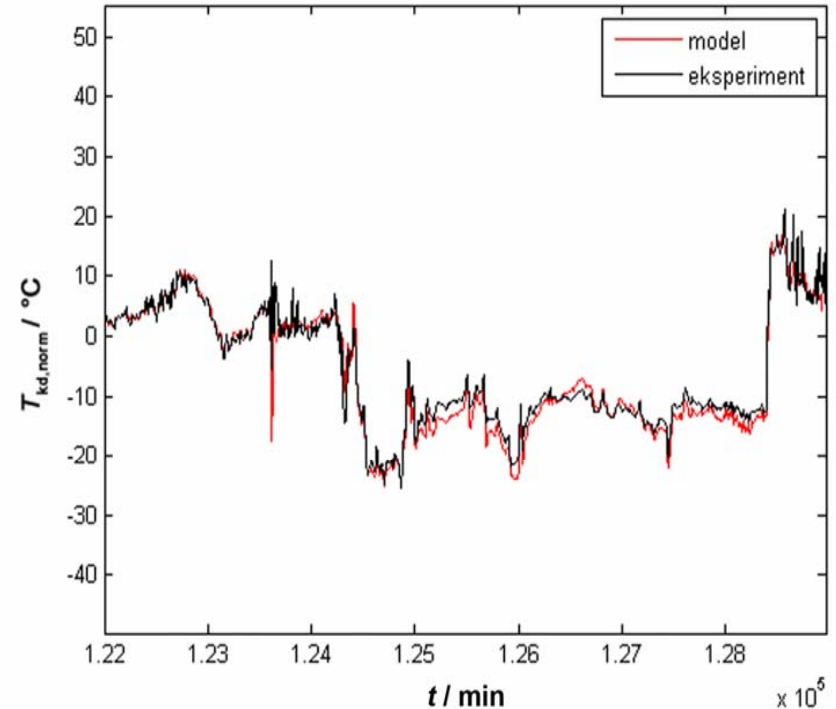
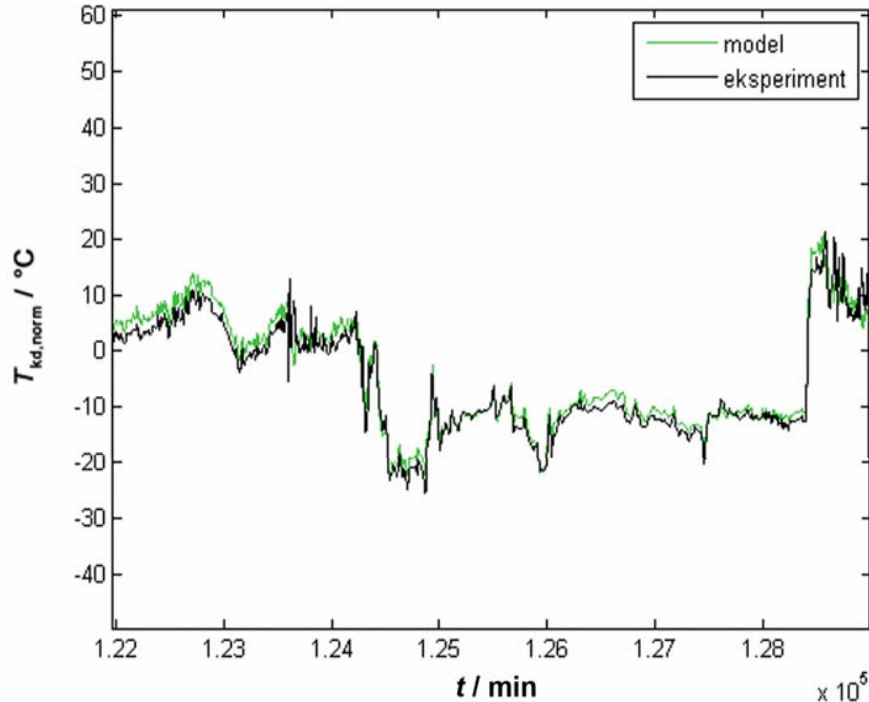
## OE model



<b><i>FIT PRED.</i></b>	<b><i>FPE</i></b>	<b>MODEL PARAMETER</b>
83,50	6,09	nb = 2, nf = 6, nk=0

# RESULTS - Nonlinear dynamic models (D95)

## HW and NARX model with sigma neural networks



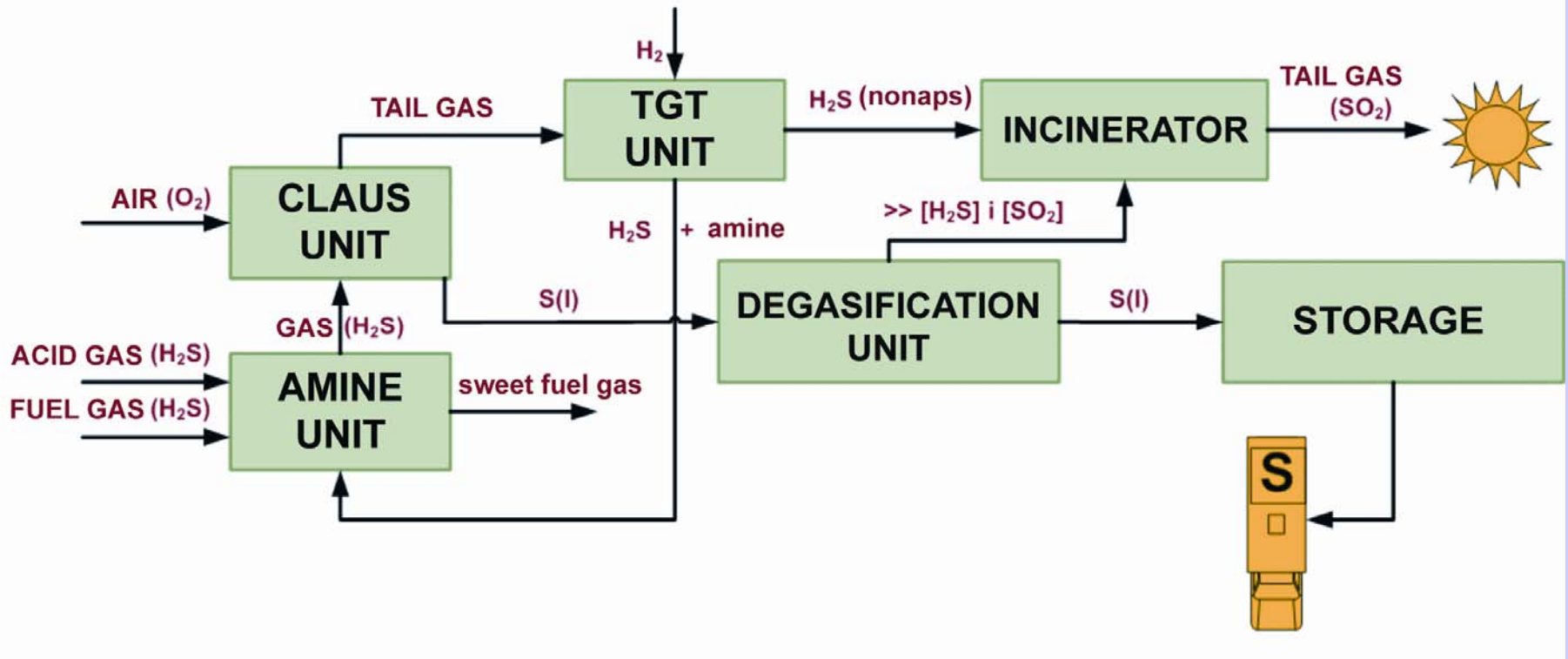
<i><b>FIT PRED.</b></i>	<i><b>FPE</b></i>	<b>MODEL PARAMETER</b>
81,07	4,97	nb = 2, nf =3, nk=0

<i><b>FIT PRED.</b></i>	<i><b>FPE</b></i>	<b>MODEL PARAMETER</b>
88,73	1,09	na = 7, nb =6, nk=0

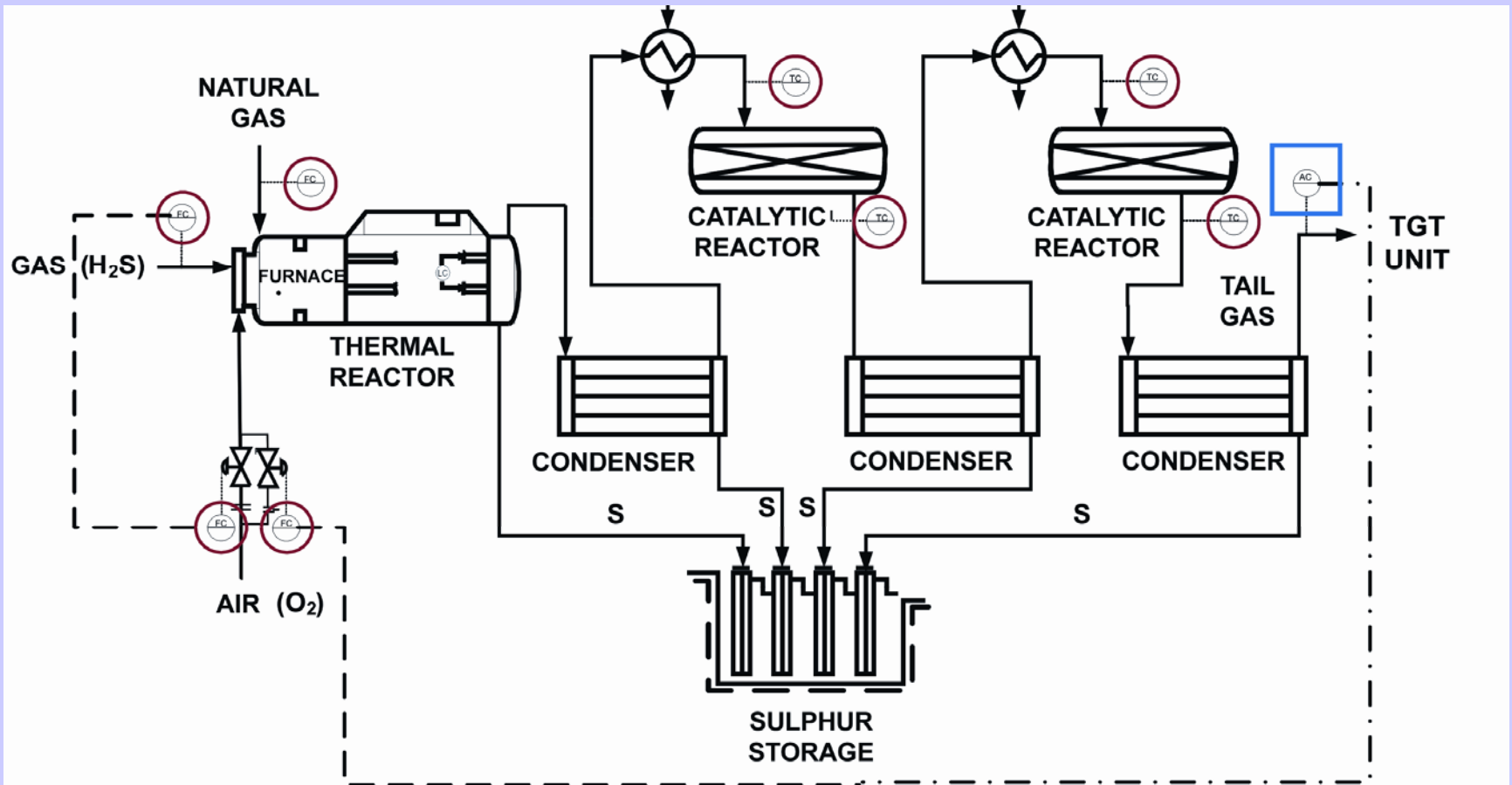
# SULPHUR RECOVERY UNIT (SRU) INA - SISAK RAFINERY



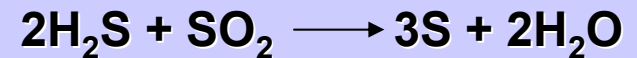
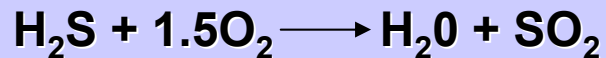
# SULPHUR RECOVERY UNIT



# CLAUS SECTION



## SIMPLIFIED REACTION MECHANISM:



# H<sub>2</sub>S and SO<sub>2</sub> ANALYZER

**Type of analysis:** UV photometry

**Accuracy:** ± 2% (SO<sub>2</sub> i H<sub>2</sub>S) P.O.

**Response:** 90% < 15 s

**Outputs**

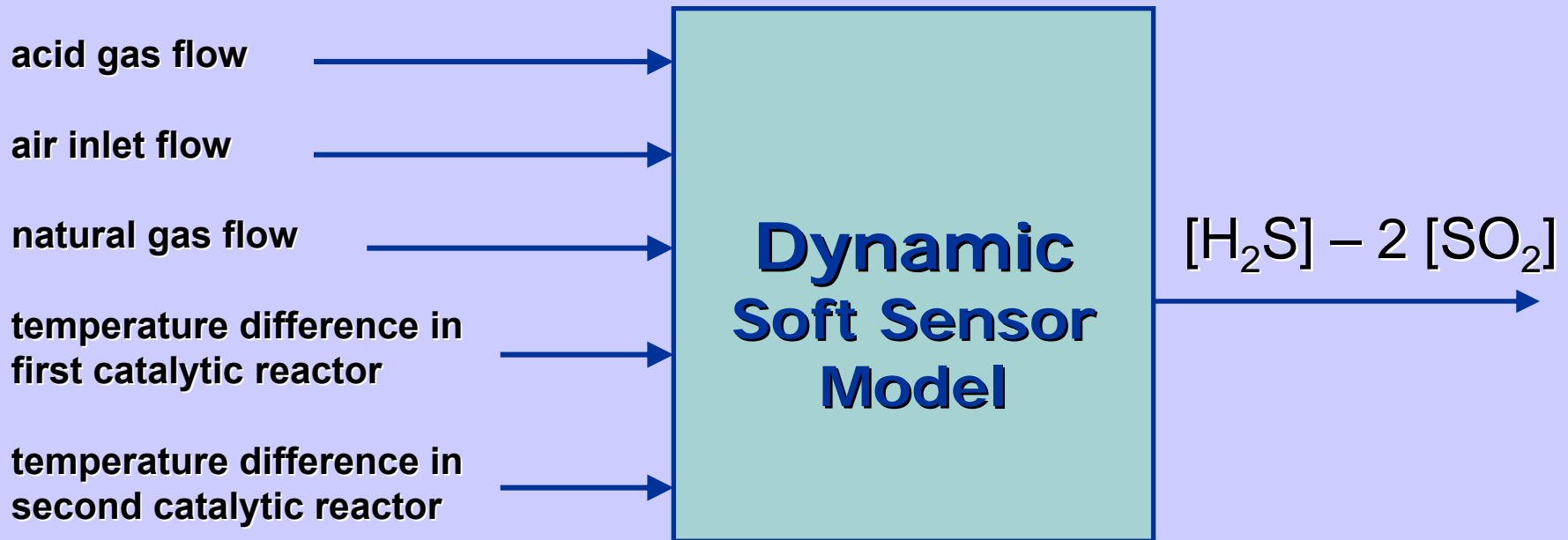
- vol.% SO<sub>2</sub>
- vol.% H<sub>2</sub>S
- vol.% surplus SO<sub>2</sub>, H<sub>2</sub>S

**Out of service**

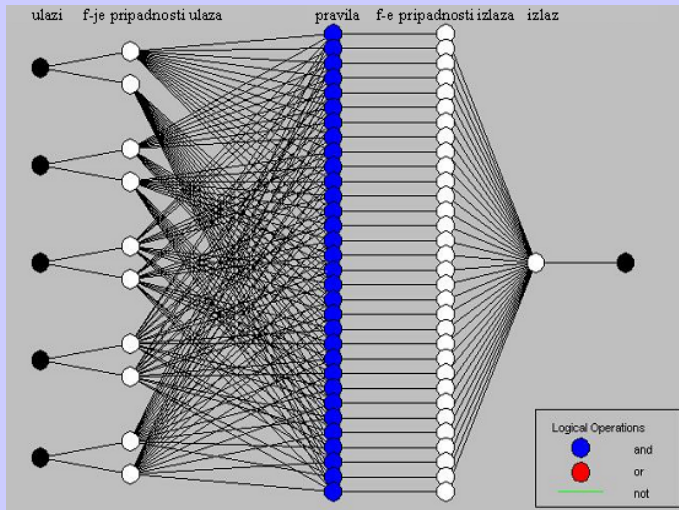
- problems with the sampling system
- problems with the analyzer



# SOFT SENSOR FOR PROCESS CONTROL

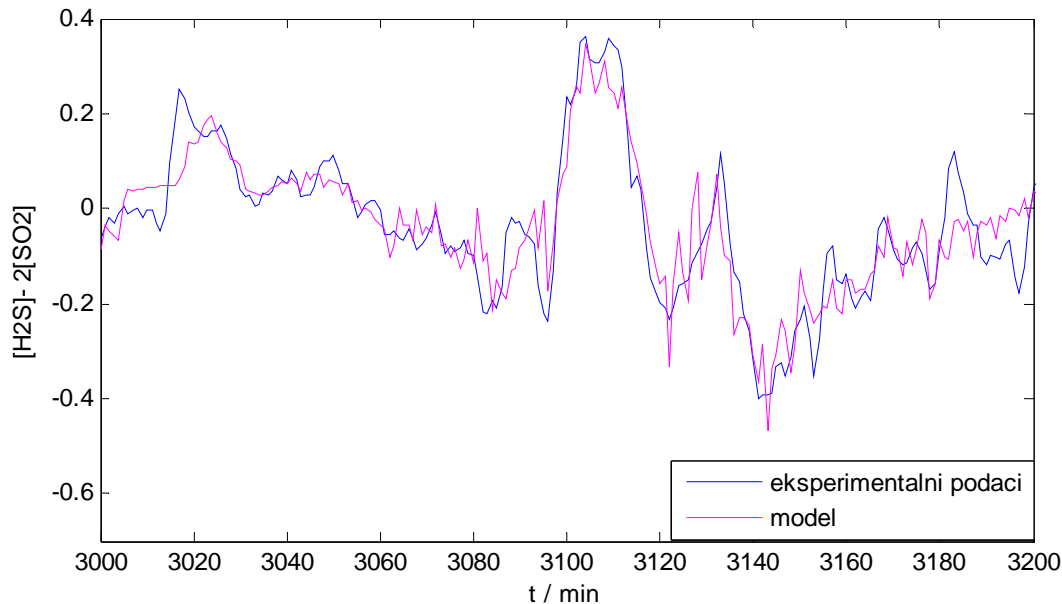


# SOFT SENSOR FOR CLAUS PROCESS



## NEURO-FUZZY MODEL

- combined neural network and fuzzy logic
- each of five inputs has two membership function
- by combining  $2^5$  fuzzy rules are obtained



model validation

# CONCLUSION

## BENEFITS OF SOFT SENSORS

- ✚ Feedforward information from inferential measurement
- ✚ More consistent production
- ✚ Better process control
- ✚ Increased scope for process optimization

# CONCLUSION

- ✚ Data-driven soft sensors help to improve the operation of chemical processes and to drive them towards optimality.
- ✚ The necessary infrastructure (DCS, PIMS, LIMS) is needed
- ✚ The number of reported applications of data-driven models is growing.
- ✚ In most industrial cases linear and steady-state models are applied.
- ✚ Continuous exchange between academia and industry is permanently required in order to develop new application.

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# SOFT SENSORS APPLICATION IN PROCESS INDUSTRY



THANKS FOR YOUR ATTENTION !

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